

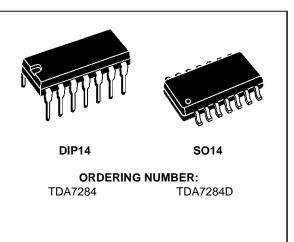
RECORD/PLAYBACK CIRCUIT WITH ALC

ADVANCE DATA

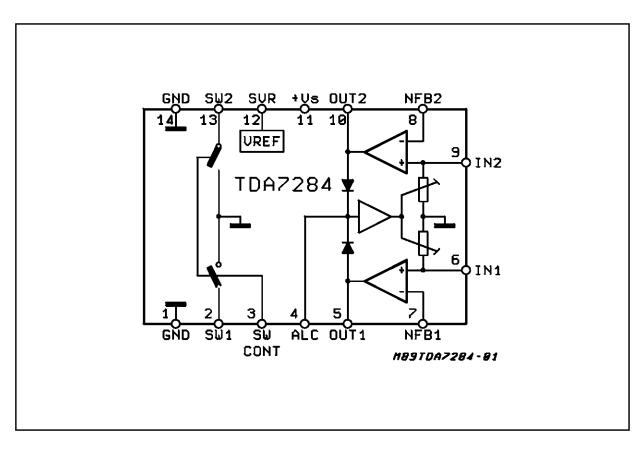
- WIDE OPERATING SUPPLY VOLTAGE (3V to 12V)
- VERY LOW INPUT NOISE ($V_1 = 1.2\mu V$)
- INTERNAL COMPENSATION FOR HIGH GAIN APPLICATION (DOUBLE SPEED RE-CORDING)
- BUILT-IN ALC CIRCUITRY
- GOOD SVR
- DC CONTROLLED SWITCHES FOR MUTE OR EQUALIZATION SWITCHING FUNC-TIONS

DESCRIPTION

The TDA7284 is a monolithic integrated circuit in a DIP/SO-14 designed for 6V, 9V and 12V AC/DC portable cassette equipment application.



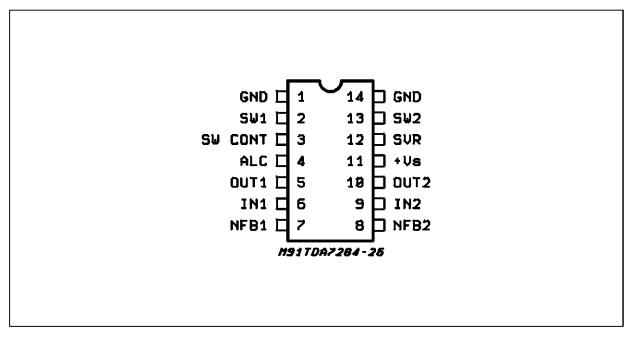
BLOCK DIAGRAM



October 1993

This is advanced information on a new product now in development or undergoing evaluation. Details are subject to change without notice.

PIN CONNECTION (Top view)



ABSOLUTE MAXIMUM RATINGS

Symbol	Parameter	Value	Unit
Vs	Supply Voltage	14	V
T _{OP}	Operating Temperature Range	-20 to 70	°C
T _{stg} , T _j	Storage and Junction Temperature Range	-40 to 150	°C

THERMAL DATA

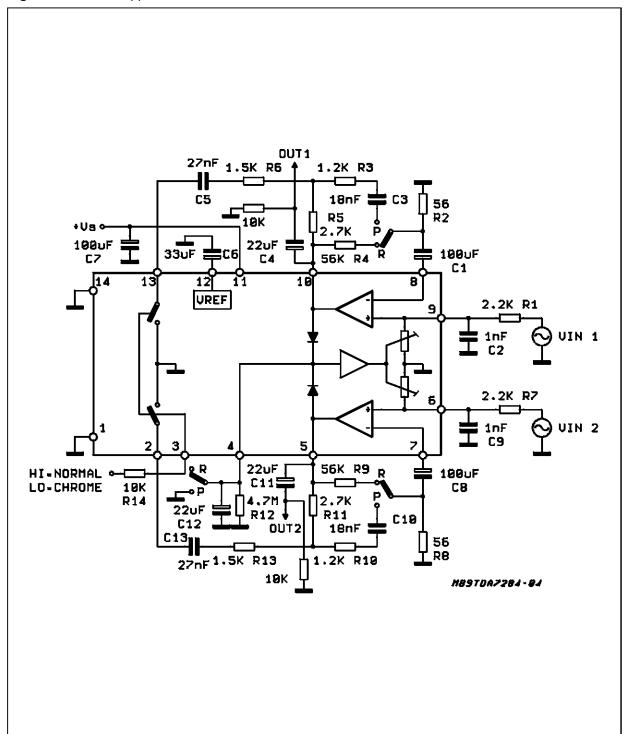
Symbol	Description	S014	DIP14	Unit
R _{th} j-amb	Thermal Resistance Junction-ambient	200	120	°C/W

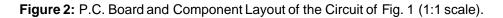
DC CHARACTERISTICS ($T_{amb} = 25^{\circ}$; $V_S = 6V$; $V_i = 0V$; $R_i = 10K\Omega$; ALC = OFF)

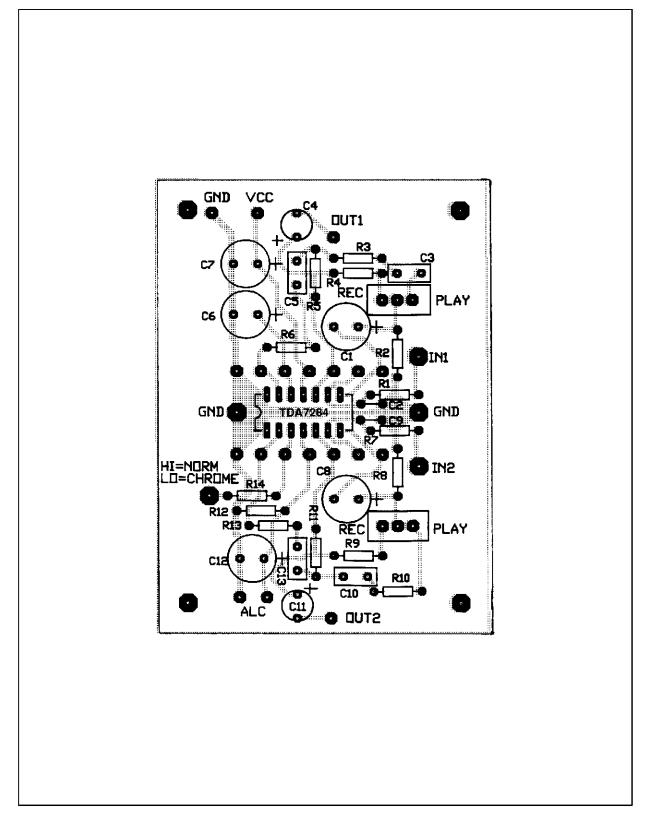
Terminal No.	1	2	3	4	5	6	7	8	9	10	11	12	13	14
Terminal Voltage (V)	0	0	0	0	2.6	0	1.3	1.3	0	2.6	6	4.6	0	0



Figure 1: Test and Application Circuit









Symbol	Parameter	Test Condit	ion	Min.	Тур.	Max.	Unit
Vs	Supply Voltage			3		12	V
ld	Quiescent Current						mA
En	Input Noise	$\begin{array}{l} R_{g} = 2.2K\Omega\\ BW = 22Hz \text{ to } 22kH \end{array}$	$R_g = 2.2K\Omega$ BW = 22Hz to 22kHz				μV
RI	Input Resistance			30	50	70	KΩ
Go	Open Loop Gain						dB
Vo	Output Voltage	THD <u><</u> 1%	THD ≤ 1% ALC OFF ALC ON		1.8 0.9	1.1	V _{rms} V _{rms}
THD	Total Harmonic Distortion	$V_O = 1V_{rms}$ ALC = ON $V_I = 100$	$V_{O} = 1V_{rms}$ ALC = ON V _I = 100mV			0.5 1	% %
	ALC Range	$\Delta V_{O} = 3 dB$	$\Delta V_{O} = 3 dB$		47		dB
СВ	Channel Balance	ALC ON			0	2	dB
SVR	Supply Voltage Rejection		$ \begin{array}{l} f=120Hz,C_{SVR}=33\mu F\\ V_R=100mV,R_g=10K\Omega\\ ALC=Off \end{array} $				dB
CS	Cross-talk	ALC OFF	ALC OFF				dB
Pin 3	Turn Off Threshold	I ₀ = <1μA	$I_0 = <1\mu A$				V
Pin 3	Turn On Threshold					2.25	V
Pin 3	Turn On Saturation	$R_L = 10K\Omega$			0.1	0.2	V

ELECTRICAL CHARACTERISTICS (Vs = 6V, T_{amb} = 25°C unless otherwise specified refer to test circuit)

Figure 3: Drain Current vs. Supply Voltage

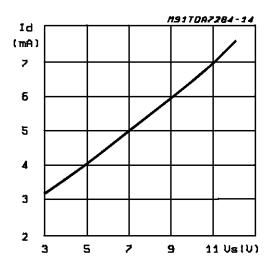
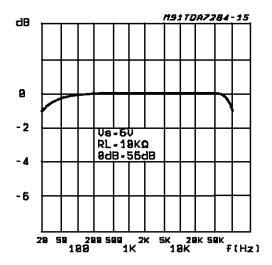


Figure 4: Recording Closed Loop Gain vs. Frequency





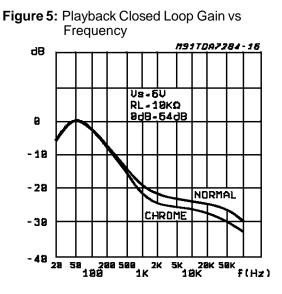


Figure 7: Output Voltage vs. Input Voltage

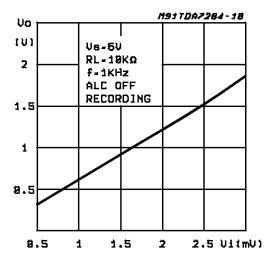


Figure 9: Output Voltage vs. Input Voltage

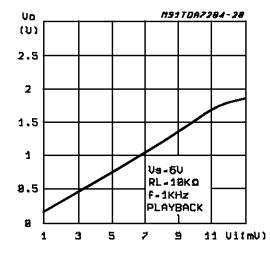


Figure 6: Normalized Output Voltage vs. Supply Voltage

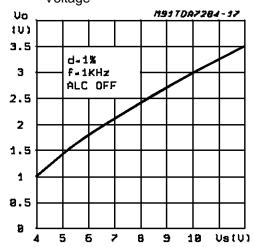


Figure 8: Output Voltage vs. Input Voltage

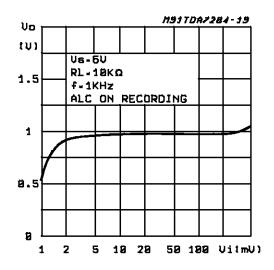


Figure 10: Distortion vs. Input Voltage

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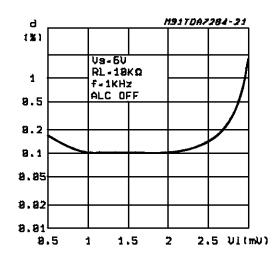


Figure 11: Distortion vs. Input Voltage

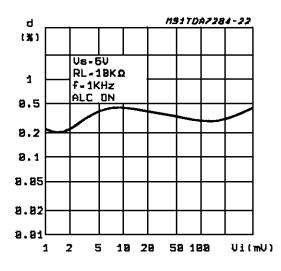


Figure 13: Crosstalk vs. Frequency (ALC = Off)

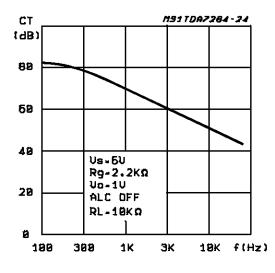


Figure 12: SVR vs. Frequency (ALC = Off)



1K

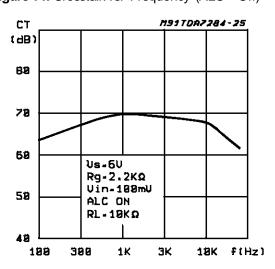
ЗК

F(Hz)

399

40

100



CIRCUIT DESCRIPTION

OPERATIONAL AMPLIFIER

The operational amplifier consists essentially of a very low noise input stage decoupled from the

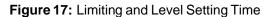
Figure 15

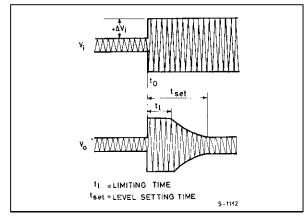
by means of a peak-to-peak detector) into a conthe tape and which optimizes the signal to noise tinuous voltage which drives the networks indiratio even there are notable variations in the input cated by T and Rd. signal. The element T transforms the continuous voltage Before presenting the ALC circuit of TDA7284 it is level into a signal capable of modifying the circuit worth describing the operation of the automatic conditions symbolized by variable resistor Rd. level control as a system. A diagram showing the The value assumed by the resistor Rd is a funcbasis of operation is given in fig.16. tion of the output signal level Vo and is such that the voltage Vc at the input of the op-amp is con-Figure 16: Basic Diagram of the ALC stage stant, even variations of Vi are present. Obviously if Vo is less than a certain value the system is not controlled. In this case : $V_I = V_C = V_O / G_V$ $(G_V \text{ is the gain of the op-amp})$ For the TDA7284 the value of V_0 below which the system is not controlled is around 1 Vrms. Let us now consider the speed of response of the system (when controlled) to positive and negative changes of the input signal i.e. the limiting time, the time for return to nominal level (1 Vrms) and the recovery time. Limiting time, and time for return to nominal level.



single-ended output stage by means of an emitter follower (fig. 15).

The compensations provided in order to have high gain bandwith product allowing the use for double speed recording application.





Usually such an increase drives the op-amp into saturation and the time for which it remains in this condition is called the limiting time(T1).

T1 depends on the relationship between the external capacitances, the time constant $T=R1 \cdot C1$, the supply voltage and the signal variation.

The criteria for choosing the length of T1 are the result of several compromises. In particular if T1 is too long, there will be audible distortion during playback (during T1 the output is a square wave), and if it is too short, the sensation of increased level will be lost while dynamic compression phenomena and instability may occur.

The time for return to nominal level is defined as the total time between the instant To and the instant in which the output reassumes the nominal value. This time (Ts) is roughly equal to $5 \cdot T1$.

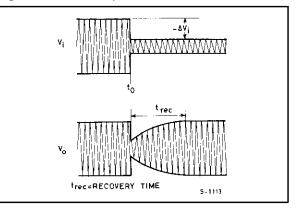
On the basis of tests carried out it has been found that a musical signal with high dynamic range



Recovery time.

let us now suppose that at the instant To the input signal decreases of ΔVi (fig. 18).

Figure 18: Recovery Time



The recovery time (Trec) is defined as the time between the instant To and the instant in which the output signal returns to the nominal level.

This time depends essentially on the discharge time constant of R2 • C2 (see fig. 16) and on the size of the step $-\Delta Vi$. In this case too, if this time is too long the signal to noise ratio on the tape deteriorates.

If it is too short the sensation of the low signal level is lost during playback.

The ALC system of the TDA7284

Fig. 16 becomes the following (fig. 19) where the

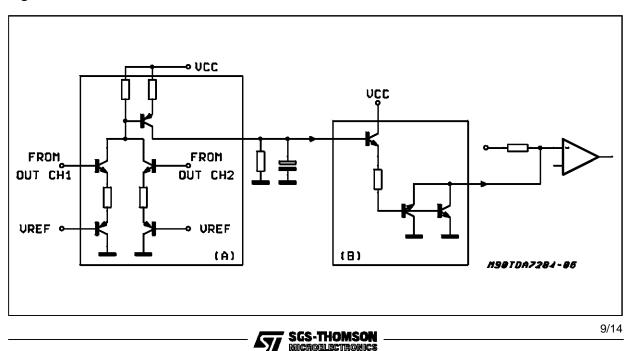


Figure 19

peak-to-peak detector of fig. 16 is now inside the broken line 1 while the system which allows a dinamic resistance varying with the DC voltage level (i.e. inversely proportional to the op-amp output signal), is inside the broken line 2.

It should be noted that the generator resistance Ri has no influence on the controlled voltage value Vc, although its value should be between 1 and 47 Kohm.

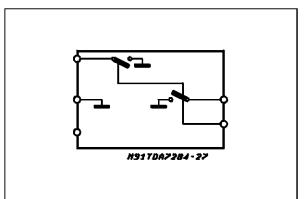
The lower limit is determined by the minimum dynamic resistance of 10 ohm and therefore to have a control range of 40 dB for the input signal, Ri must be greather than 1.5 Kohm.

The upper limit results from the necessity to limit the attenuation of the signal by the input impedance of the op-amp.

Switches

Two DC-controlled switches are also included in the chip (fig. 20)

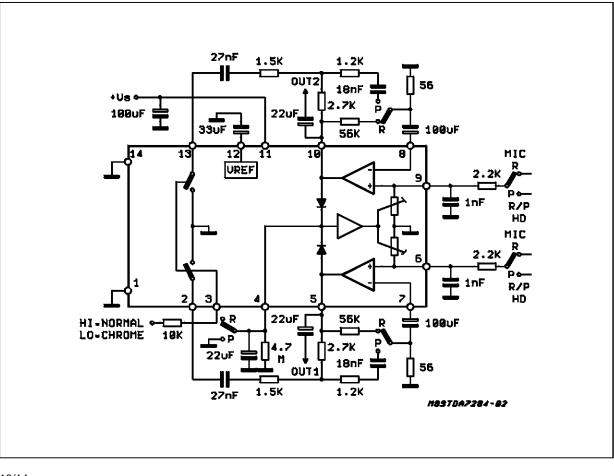
Fig. 19 shows the typical application circuit of the TDA7284 utilizing the equalization switch for normal or chrome tape playback equalization. The advantage is the components can be placed near Figure 20



to the IC, while the tape selector switch can be at a remote location, hence reduce the chances of noise and oscillation due to components layout. Another advantage is that only one pole is needed for the tape selector switch as compared to the two poles needed by conventional circuits (one separate pole for each channel).

Fig. 22 shows the use of the switches to obtain the mute function.

Figure 21: Application Circuit with DC Switching of Normal/Chrome Tape Equalization



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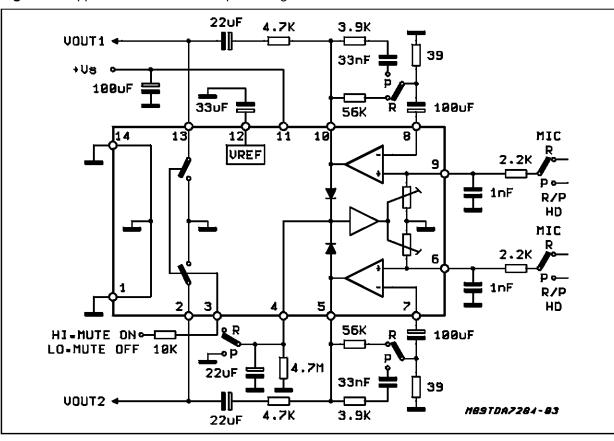


Figure 22: Application Circuit with Output Muting

SVR

A refernce circuit is enclosed to provide a stable voltage and to supply a stable current to all cur-

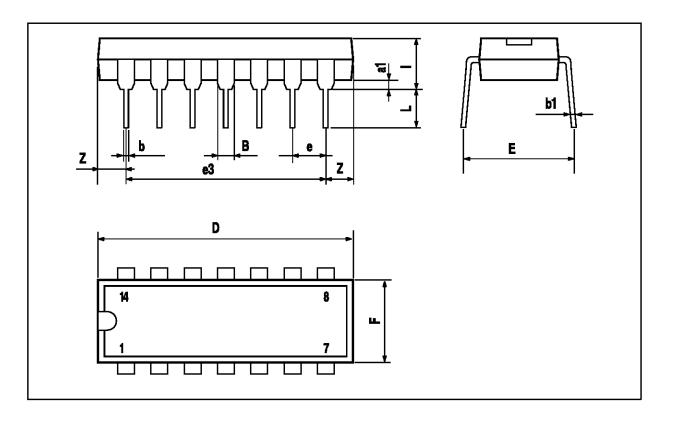
rent mirrors.

SVR capacitor is also connected to this block for good ripple rejection.



DIP14 PACKAGE MECHANICAL DATA

DIM.		mm		inch				
	MIN.	TYP.	MAX.	MIN.	TYP.	MAX.		
a1	0.51			0.020				
В	1.39		1.65	0.055		0.065		
b		0.5			0.020			
b1		0.25			0.010			
D			20			0.787		
E		8.5			0.335			
е		2.54			0.100			
e3		15.24			0.600			
F			7.1			0.280		
I			5.1			0.201		
L		3.3			0.130			
Z	1.27		2.54	0.050		0.100		





SO14 PACKAGE MECHANICAL DATA

DIM.		mm		inch							
Diwi.	MIN.	TYP.	MAX.	MIN.	TYP.	MAX.					
А			1.75			0.069					
a1	0.1		0.2	0.004		0.008					
a2			1.6			0.063					
b	0.35		0.46	0.014		0.018					
b1	0.19		0.25	0.007		0.010					
С		0.5			0.020						
c1			45°	(typ.)							
D	8.55		8.75	0.336		0.344					
E	5.8		6.2	0.228		0.244					
е		1.27			0.050						
e3		7.62			0.300						
F	3.8		4.0	0.15		0.157					
L	0.5		1.27	0.020		0.050					
М			0.68			0.027					
S		8° (max.)									

